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Infrasound Propagation in Multiple-Scale Random Media Using Generalized Polynomial Chaos

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#### The Atmospheric uncertainties

#### Atmospheric Specification (AS):

- Background state provided by numerical weather forecasts / atmospheric climate reanalysis.
- Fluctuations of those profiles (like Gavity Waves) are not resolved in ECMWF, G2S, ...
- Uncertainties associated with AS:
  - Can be reduced using SVD decomposition
  - Described by a vector  $\boldsymbol{\xi} \in \mathbb{R}^d$
- Assessing the impact of ξ on infrasound/acoustic propagation:
  - Deviation from mean state is large but d < 10.
  - For computational model parameters θ, Y = F(X(ξ); θ) can be represented using a metamodel.





#### **Outline of the Presentation**

## Polynomial Chaos based Metamodel

- What is a Metamodel ?
- The Polynomial Chaos (gPC) Framework

# Planetary Boundary Layer (PBL) as a Validation Case

- PBL with a Nocturnal Jet
- Normal Modes Decomposition
- Random Modes and Random Wavepackets
- Performance of the Metamodel

## O Towards a more Realistic Atmosphere

- Incorporating Small-Scale Fluctuations
- Possible Use of the Metamodel



# On the use of a Metamodel

Build a metamodel  $\hat{F}$  of  $Y = F(X(\xi); \theta)$  where  $\xi \sim \mathcal{N}(0, \mathbb{I}_n)$ :



Characteristics of a metamodel:

- Calibrated using a small number of runs of the expensive code.
- Easy to assess numerically.
- Reproduce the statistical properties of the output.
- Application to infrasound propagation:
  - Forward uncertainty propagation: Y is a signal at a given distance R
  - Association or localization: Y is a set of by-products (duration, amplitude, ...)



#### **Polynomial Chaos decomposition**

A non-intrusive metamodel of  $Y = F(X(\xi); \theta)$  where  $\xi \sim \mathcal{N}(0, I_n)$ 

- Polynomial chaos decomposition:
  - $Y = \sum_{j \in J} a_j H_j(\xi)$  and  $a_j = \langle Y, H_j \rangle$ ,
    - (*H<sub>j</sub>*)<sub>*j*∈*J*</sub> set of polynomials (up to degree *d*)
    - (*H<sub>j</sub>*)<sub>*j*∈*J*</sub> orthonormals for inner product ⟨*f*, *g*⟩ = ℝ[*fg*].
- Cross-validation for order (|J|) selection: Leave-One-Out procedure.



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#### Nocturnal jet seen as a perturbation:

• PBL model from Waxler 2008\* + random nocturnal jet *u<sub>J</sub>*:

$$u_J(z,\xi) = \mathbf{a} \times \mathbf{e}^{\frac{z-z_J}{\sigma^2}}$$

$$ightarrow$$
 Effective celerity:  $c(z,\xi) = c_0(z) + u_J(z,\xi)$ 

• Uncertainties on the jet properties:

$$\left. egin{array}{l} a \sim \mathcal{N}(m_a, s_a) \ \sigma \sim \mathcal{N}(m_\sigma, s_\sigma) \end{array} 
ight\} \Rightarrow \xi = (a, \sigma) \in \mathbb{R}^2$$

Numerical setup:

- Wave propagation with normal modes (FLOWS).
- Perfectly Matched Layer used at  $z \rightarrow \infty$
- Neumann homogeneous condition at the ground.
- Std of the parameters  $\rightarrow \sim$  7% of fluctuation on the profil.





## The acoustic modes

Wave equation:  $H\Psi = k^2 \Psi$ :  $\sigma(H) = \sigma_{disc}(H) \oplus \sigma_{cont}(H)$ 

Green function at distance R.



Random medium: c(z) gives  $(k_l, \Psi_l(z))$ 

365

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The spectrum of H(ξ) consists in random variables k<sub>l</sub>(ξ) that may be difficult to follow as ξ varies:





PDF of  $G_i(\omega, \xi)$  as a function of  $\xi$  depends on the mode number *i*.

Source is fixed and deterministic, we only look at variability generated by the random medium.



**9**PC expansion for  $Y = (k_{l}(\xi), \Psi_{l}(z, \xi))_{l=1,...,N}:$ •  $\tilde{K}_{l}(\xi) = \sum_{j \in J} a_{j}^{k_{l}} H_{j}(\xi)$ •  $\tilde{\Psi}_{l}(z, \xi) = \sum_{j \in J} a_{j}^{\Psi_{l}}(z) H_{j}(\xi)$ 

 $\Rightarrow$  Metamodel for s(t).



About convergence of signals  $\tilde{s}(t,\xi)$  produced by the gPC-metamodel.

- (1) gPC provides convergence in L<sup>2</sup>-norm and (2) G depends continuously on k<sub>l</sub> and Ψ<sub>l</sub>. Hence ||G̃ - G||<sub>2</sub> <sup>P→∞</sup>→ 0.
- $\mathscr{F}$  is an  $L^2$ -isometry and thus,  $||\tilde{s}(t,\xi) s(t,\xi)||_2 \xrightarrow{P \to \infty} 0$ .

Comparison of gPC and Monte-Carlo simulations:



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#### Impact of small-scale fluctuations

- Atmospheric perturbations include large deviation and turbulent noise: c(z, ξ) = c<sub>0</sub>(z, ξ) + εc<sub>1</sub>(z):
- The impact of the turbulent noise can be modelled using the coupling matrix (C<sub>nm</sub>)<sub>n,m</sub>

$$p \sim \sum_{n=1}^{N} \frac{\phi_{n0}^{2}(\xi) e^{ik_{n0}(\xi)r}}{\sqrt{Rk_{n0}(\xi)}} \left(1 + i\sqrt{\varepsilon}R\frac{\omega^{2}C_{nn}(\xi)}{2k_{n0}(\xi)}\right) + \sum_{n=1}^{N} \sum_{m=1}^{N} F((\xi))$$

The coupling matrix depends on the large scale perturbations, its gPC expansion can be derived from  $\phi_{n0} = \sum_{k=0}^{+\infty} \alpha_k^{(n)}(z) H_k(\xi)$ :

$$\frac{\boldsymbol{C}_{nl}}{\boldsymbol{C}_{nl}} = \sum_{k=0}^{+\infty} \gamma_k^{(nl)} H_k(\xi) \text{ where } \gamma_p^{(nl)} = \sum_{j,k} \langle \frac{\mu(z)\alpha_j^{(n)}(z)}{c_0^2(z)}, \alpha_k^{(l)}(z) \rangle \mathbb{E}\left[H_j H_k H_p\right]$$





## Take-Home Messages

- **I** gPC framework is an efficient way to obtain a metamodel for complex signals unless  $d \gg 10$ .
- One metamodel per IMS station provides a way for localization and association procedures, provided a first guess is available.
- Since the metamodel does not depend on source signal it can be used together with a random incoming signal (e.g. Microbarom) with no supplementary cost.

